

① 2 marks

$$H(j\omega)$$

\uparrow
 \downarrow

a) $y(t) = x_1(t) * h(t) - x_2(t)$

i) let $x_1(t) \rightarrow y_1(t) = x_1(t) * h(t) - x_1(t)$
 $x_2(t) \rightarrow y_2(t) = x_2(t) * h(t) - x_2(t)$

Then $a x_1(t) + b x_2(t) \rightarrow (a x_1(t) + b x_2(t)) * h(t)$
 $- a x_1(t) - b x_2(t)$

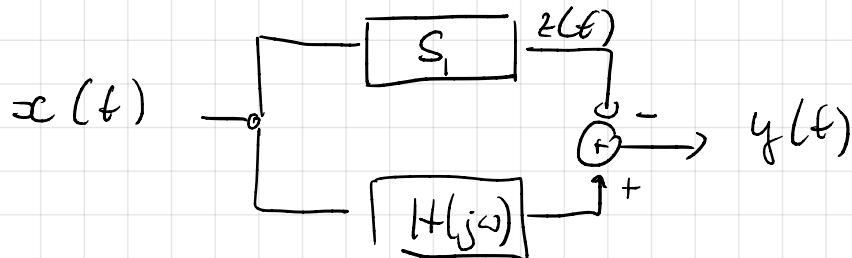
$$\begin{aligned} &= a x_1(t) * h(t) - x_1(t) \\ &\quad + b x_2(t) * h(t) - x_2(t) \\ &= a y_1(t) + b y_2(t) \end{aligned}$$

\Rightarrow linear //

ii) $x_1(t-\tau) \rightarrow x_1(t-\tau) * h(t) + x_1(t-\tau)$
 $= y_1(t-\tau)$

\Rightarrow time invariant //

OR:



where system S_1 : $z(t) = x(t)$

System S_1 is obviously LTI.

The SoT is parallel concatenation
of 2 LTI systems. Therefore, it is LTI. //

(b) $y(t) = x(t) * h(t) - xc(t)$

2 marks $Y(j\omega) = X(j\omega) \cdot H(j\omega) - X(j\omega)$

$$H_{SOT}(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = H(j\omega) - 1 //$$

(c) Ideal high pass filter:

2 marks

$$H_{SOT}(j\omega) = \begin{cases} 1 & \text{for } |\omega| > \omega_c \\ 0 & \text{for } |\omega| < \omega_c \end{cases}$$

$$\Rightarrow H(j\omega) = \begin{cases} 2 & \text{for } |\omega| > \omega_c \\ 1 & \text{for } |\omega| < \omega_c \end{cases}$$

also ok: $H_{SOT}(j\omega) = \begin{cases} -1 & |\omega| > \omega_c \\ 0 & |\omega| < \omega_c \end{cases}$ [↑]
equal sign can be

$$H(j\omega) = \begin{cases} 0 & |\omega| > \omega_c \\ 1 & |\omega| < \omega_c \end{cases}$$
 anywhere

2

1.5 marks
each

a)

$y[n]$ is independent of
 $x[2] \Rightarrow$ not invertible

(Def $x_1[n] = x_2[n] \forall n \neq 2$
and $x_1[2] \neq x_2[2]$.)

Then $y_1[n] = y_2[n]$.)

b) Let $x_1(t) = x_2(t) + a$,
where $a \neq 0$.

Then, $y_1(t) = y_2(t)$ (but $x_1(t) \neq x_2(t)$)
 \Rightarrow not invertible

c) Def $x_1[n] = 2 \forall n$
and $x_2[n] = -2 \forall n$

Then $y_1[n] = y_2[n] = 4 \forall n$
 \Rightarrow not invertible

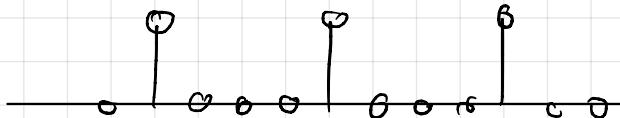
S: $y[n] = \begin{cases} x_1[n/2] & \text{even} \\ 0 & \text{odd} \end{cases}$

We can find an inverse system: $S^{-1}: y[n] = x_1[2n]$

That is: $x[n] \xrightarrow{\boxed{S}} y[n] \xrightarrow{\boxed{S^{-1}}} x[2n]$

\Rightarrow invertible

(3)

 $x[n] :$ 

(a)

Period $N = 4$ // 1 mark

$$c_k = \frac{1}{4} \sum_{n=0}^3 \delta[n] e^{-jk\frac{2\pi}{4}n}$$

$$= \frac{1}{4} \checkmark k // 2 \text{ marks}$$

(b)

$$y[n] = x[n] * h[n]$$

3 marks



$$\sum a_n e^{j\frac{2\pi}{N}n} = \sum c_n e^{j\frac{2\pi}{N}n} H(e^{j\frac{2\pi}{N}n})$$

$$a_n = c_n H(e^{j\frac{2\pi}{N}n})$$

$$\begin{aligned} H(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} h[n] e^{-jn\omega} \\ &= e^{-j\omega} + 1 + e^{j\omega} \end{aligned}$$

Can also leave

it as exponential = $1 + 2 \cos(\omega)$

$$H(e^{j\frac{\pi}{2}k}) = 1 + 2 \cos(k\frac{\pi}{2})$$

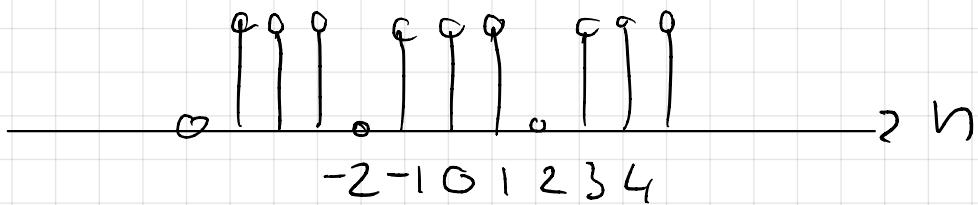
$$a_n = \frac{1}{4} (1 + 2 \cos(n\frac{\pi}{2}))$$

$$\text{alternatively: } y[n] = x[n] * h[n]$$

$$= \sum (\delta[n-4k]$$

$$\delta[n-4k-1]$$

$$\delta[n-4k+1])$$



$$a_k = \frac{1}{4} \sum_{n=-1}^1 e^{j \frac{2\pi}{4} k} = \frac{1}{4} \left(1 + e^{j \frac{\pi}{2} k} + e^{j \frac{3\pi}{2} k} \right)$$

$$= \frac{1}{4} \left(1 + 2 \cos\left(\frac{\pi}{2}k\right) \right)$$

also ok:

$$= \frac{1}{4} \left(1 + e^{j \frac{\pi}{2} k} + e^{j \frac{3\pi}{2} k} \right)$$

$$(4) \quad Y_1(j\omega) = H_1(j\omega) X(j\omega)$$

4 marks

$$X(j\omega) = \pi [\delta(\omega-1) + \delta(\omega+1)]$$

$$\begin{aligned} (i) \quad H_1(j\omega) &= \frac{1}{j\omega} + \pi \delta(\omega) - \frac{1}{2} 2\pi \delta(\omega) \\ &= \frac{1}{j\omega} \end{aligned}$$

$$\Rightarrow Y_1(j\omega) = \frac{\pi}{j\omega} [\delta(\omega-1) + \delta(\omega+1)]$$

$$= \frac{\pi}{j} [\delta(\omega-1) - \delta(\omega+1)]$$

$$\Rightarrow y_1(t) = \sin(t)$$

$$(ii) \quad H_2(j\omega) = -2 + \frac{5}{2+j\omega}$$

$$\begin{aligned} \Rightarrow Y_2(j\omega) &= \pi \left[\underbrace{\left(-2 + \frac{5}{2+j} \right)}_{1/j} \delta(\omega-1) \right. \\ &\quad \left. + \underbrace{\left(-2 + \frac{5}{2-j} \right)}_{-1/j} \delta(\omega+1) \right] \end{aligned}$$

$$= \frac{\pi}{j} [\delta(\omega-1) - \delta(\omega+1)]$$

$$\Rightarrow y_2(t) = \sin(t)$$

(b) e.g. $h_3(t) = \frac{1}{2}h_1(t) + h_2(t)$

2marks