

VECTOR DERIVATIVES

Cartesian $d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}, \quad d\tau = dx dy dz$

Gradient: $\nabla t = \frac{\partial t}{\partial x} \hat{\mathbf{x}} + \frac{\partial t}{\partial y} \hat{\mathbf{y}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence: $\nabla \cdot \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

Curl: $\nabla \times \mathbf{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{\mathbf{x}} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{\mathbf{y}} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{\mathbf{z}}$

Laplacian: $\nabla^2 t = \frac{\partial^2 t}{\partial x^2} + \frac{\partial^2 t}{\partial y^2} + \frac{\partial^2 t}{\partial z^2}$

Spherical $d\mathbf{l} = dr \hat{\mathbf{r}} + r d\theta \hat{\boldsymbol{\theta}} + r \sin \theta d\phi \hat{\boldsymbol{\phi}}, \quad d\tau = r^2 \sin \theta dr d\theta d\phi$

Gradient: $\nabla t = \frac{\partial t}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial t}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}}$

Divergence: $\nabla \cdot \mathbf{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$

Curl: $\nabla \times \mathbf{v} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{\mathbf{r}} + \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\boldsymbol{\theta}} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\boldsymbol{\phi}}$

Laplacian: $\nabla^2 t = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial t}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial t}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 t}{\partial \phi^2}$

Cylindrical $d\mathbf{l} = ds \hat{\mathbf{s}} + s d\phi \hat{\boldsymbol{\phi}} + dz \hat{\mathbf{z}}, \quad d\tau = s ds d\phi dz$

Gradient: $\nabla t = \frac{\partial t}{\partial s} \hat{\mathbf{s}} + \frac{1}{s} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence: $\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$

Curl: $\nabla \times \mathbf{v} = \left[\frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{\mathbf{s}} + \left[\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\boldsymbol{\phi}} + \frac{1}{s} \left[\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{\mathbf{z}}$

Laplacian: $\nabla^2 t = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial t}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 t}{\partial \phi^2} + \frac{\partial^2 t}{\partial z^2}$

VECTOR IDENTITIES

Triple Products

(1) $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})$

(2) $\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B}(\mathbf{A} \cdot \mathbf{C}) - \mathbf{C}(\mathbf{A} \cdot \mathbf{B})$

Product Rules

(3) $\nabla(fg) = f(\nabla g) + g(\nabla f)$

(4) $\nabla(\mathbf{A} \cdot \mathbf{B}) = \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) + (\mathbf{A} \cdot \nabla) \mathbf{B} + (\mathbf{B} \cdot \nabla) \mathbf{A}$

(5) $\nabla \cdot (f\mathbf{A}) = f(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot (\nabla f)$

(6) $\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$

(7) $\nabla \times (f\mathbf{A}) = f(\nabla \times \mathbf{A}) - \mathbf{A} \times (\nabla f)$

(8) $\nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla) \mathbf{A} - (\mathbf{A} \cdot \nabla) \mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A})$

Second Derivatives

(9) $\nabla \cdot (\nabla \times \mathbf{A}) = 0$

(10) $\nabla \times (\nabla f) = \mathbf{0}$

(11) $\nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$

FUNDAMENTAL THEOREMS

Gradient Theorem: $\int_a^b (\nabla f) \cdot d\mathbf{l} = f(\mathbf{b}) - f(\mathbf{a})$

Divergence Theorem: $\int (\nabla \cdot \mathbf{A}) d\tau = \oint \mathbf{A} \cdot d\mathbf{a}$

Curl Theorem: $\int (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = \oint \mathbf{A} \cdot d\mathbf{l}$

BASIC EQUATIONS OF ELECTRODYNAMICS

Maxwell's Equations

In general:

$$\begin{cases} \nabla \cdot \mathbf{E} = \frac{1}{\epsilon_0} \rho \\ \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \\ \nabla \cdot \mathbf{B} = 0 \\ \nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \end{cases}$$

In matter:

$$\begin{cases} \nabla \cdot \mathbf{D} = \rho_f \\ \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \\ \nabla \cdot \mathbf{B} = 0 \\ \nabla \times \mathbf{H} = \mathbf{J}_f + \frac{\partial \mathbf{D}}{\partial t} \end{cases}$$

Auxiliary Fields

Definitions:

$$\begin{cases} \mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} \\ \mathbf{H} = \frac{1}{\mu_0} \mathbf{B} - \mathbf{M} \end{cases}$$

Linear media:

$$\begin{cases} \mathbf{P} = \epsilon_0 \chi_e \mathbf{E}, & \mathbf{D} = \epsilon \mathbf{E} \\ \mathbf{M} = \chi_m \mathbf{H}, & \mathbf{H} = \frac{1}{\mu} \mathbf{B} \end{cases}$$

Potentials

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t}, \quad \mathbf{B} = \nabla \times \mathbf{A}$$

Lorentz Force Law

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Energy, Momentum, and Power

Energy: $U = \frac{1}{2} \int (\epsilon_0 E^2 + \frac{1}{\mu_0} B^2) d\tau$

Momentum: $\mathbf{P} = \epsilon_0 \int (\mathbf{E} \times \mathbf{B}) d\tau$

Poynting vector: $\mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B})$

Larmor formula: $P = \frac{\mu_0}{6\pi c} q^2 a^2$

FUNDAMENTAL CONSTANTS

$$\begin{aligned} \epsilon_0 &= 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2 && \text{(permittivity of free space)} \\ \mu_0 &= 4\pi \times 10^{-7} \text{ N/A}^2 && \text{(permeability of free space)} \\ c &= 3.00 \times 10^8 \text{ m/s} && \text{(speed of light)} \\ e &= 1.60 \times 10^{-19} \text{ C} && \text{(charge of the electron)} \\ m &= 9.11 \times 10^{-31} \text{ kg} && \text{(mass of the electron)} \end{aligned}$$

SPHERICAL AND CYLINDRICAL COORDINATES

Spherical

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \sin \theta \cos \phi \hat{\mathbf{r}} + \cos \theta \cos \phi \hat{\boldsymbol{\theta}} - \sin \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{y}} = \sin \theta \sin \phi \hat{\mathbf{r}} + \cos \theta \sin \phi \hat{\boldsymbol{\theta}} + \cos \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{z}} = \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\boldsymbol{\theta}} \end{cases}$$

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1}(\sqrt{x^2 + y^2}/z) \\ \phi = \tan^{-1}(y/x) \end{cases} \quad \begin{cases} \hat{\mathbf{r}} = \sin \theta \cos \phi \hat{\mathbf{x}} + \sin \theta \sin \phi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}} \\ \hat{\boldsymbol{\theta}} = \cos \theta \cos \phi \hat{\mathbf{x}} + \cos \theta \sin \phi \hat{\mathbf{y}} - \sin \theta \hat{\mathbf{z}} \\ \hat{\boldsymbol{\phi}} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \end{cases}$$

Cylindrical

$$\begin{cases} x = s \cos \phi \\ y = s \sin \phi \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \cos \phi \hat{\mathbf{s}} - \sin \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{y}} = \sin \phi \hat{\mathbf{s}} + \cos \phi \hat{\boldsymbol{\phi}} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$

$$\begin{cases} s = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1}(y/x) \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{s}} = \cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} \\ \hat{\boldsymbol{\phi}} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$