

Q3 Phase and Amplitude response

Note: The original question was phrased incorrectly
Phase lag: $\angle H(j\omega) < 0$ for $\omega > 0$

$$(1) \quad |H_1(j\omega)|^2 = \left| \frac{1 + j\omega/10}{1 + 10j\omega} \right|^2 = \frac{1 + \frac{\omega^2}{100}}{1 + 100\omega^2} \leq 1 \quad \forall \omega$$

\Rightarrow no amplification

$$H_1(j\omega) = \frac{(1 + j\omega/10)(1 - 10j\omega)}{1 + 100\omega^2} = \frac{1 + \omega^2 + j(\frac{\omega}{10} - 10\omega)}{1 + 100\omega^2}$$

$$\angle H_1(j\omega) = \tan^{-1} \left(\frac{\frac{\omega}{10} - 10\omega}{1 + \omega^2} \right) < 0 \quad \text{for } \omega > 0$$

\Rightarrow phase lag for $\omega > 0$

$$(2) \quad H_2(j\omega) = \frac{1}{H_1(j\omega)} \\ = \frac{1}{|H_1(j\omega)|} e^{-j \angle H_1(j\omega)}$$

\Rightarrow amplification for all ω
but no phase lag

$$(3) \quad |H_3(j\omega)| = \frac{|(1 + j\omega/10)(1 + j\omega/10)|}{|(1 + 10j\omega)(1 + 10j\omega)(1 + 10j\omega)|} = \frac{|1 + j\omega/10|^2}{|1 + 10j\omega|^3} < 1 \quad \forall \omega$$

\Rightarrow no amplification

$$\begin{aligned}
 \textcircled{4} \quad |H_4(j\omega)|^2 &= \frac{1 + \omega^2/100}{|-100\omega^2 + 10j\omega + 1|^2} = \frac{1 + \omega^2/100}{(1 - 100\omega^2)^2 + 100\omega^2} \\
 &= \frac{1 + \omega^2/100}{1 + 10^4\omega^4 - 100\omega^2} > 1 \quad \text{for } |\omega| < \frac{\sqrt{100 + \frac{1}{100}}}{100} \\
 &\quad \uparrow \\
 &\quad \text{amplification}
 \end{aligned}$$

numerically evaluate $\angle H_4(j\omega)$

$$\Rightarrow \angle H_4(j\omega) < 0 \quad \text{for } \omega > 0$$

\Rightarrow phase lag

$$\textcircled{5} \quad |H_5(j\omega)| = \frac{1 + 100\omega^2}{\left(1 - \frac{\omega^2}{100}\right)^2 + \frac{1}{25}\omega^2} \geq 1 \quad \forall \omega$$

\Rightarrow amplification

numerically evaluate $\angle H_5(j\omega)$

$$\Rightarrow \angle H_4(j\omega) < 0 \quad \text{for } \omega > 9.9 \text{ rad}$$

\Rightarrow phase lag

Q4 CT filter and phase response

① ② $H(j\omega) = \begin{cases} 1 & |\omega| \geq \omega_c \\ 0 & \text{otherwise} \end{cases}$

1 mark

overall system is LTI with

$$\begin{aligned} Y(j\omega) &= X(j\omega) - X(j\omega) H(j\omega) \\ &= X(j\omega) \underbrace{(1 - H(j\omega))} \end{aligned}$$

overall frequency response $Z(j\omega)$

$$Z(j\omega) = \begin{cases} 0 & |\omega| \geq \omega_c \\ 1 & |\omega| < \omega_c \end{cases}$$

\Rightarrow ideal lowpass filter //

① ③ $Z(j\omega) = 1 - |H(j\omega)| e^{j\phi(\omega)}$

1 mark

$$= \begin{cases} 1 - e^{j\phi(\omega)} & |\omega| \geq \omega_c \\ 1 & |\omega| < \omega_c \end{cases}$$

$\Rightarrow |Z(j\omega)|$ generally non zero for $|\omega| > \omega_c$
can be > 1 for some ω

\Rightarrow not an (ideal) lowpass filter
any more //

(2)

$$Y_1(j\omega) = H_1(j\omega) X(j\omega)$$

Remark

$$\begin{aligned} Y_2(j\omega) &= H_2(j\omega) X(j\omega) = H_1(j\omega) e^{j\omega\alpha} X(j\omega) \\ &= Y_1(j\omega) e^{j\omega\alpha} \end{aligned}$$

$$\Rightarrow y_2(t) = y_1(t + \alpha)$$

\Rightarrow system 2 shifts the output compared
to system 1 //

($\alpha < 0$: shift = delay
 $\alpha > 0$: shift = advance)

Q5 DTFT System Cascade

$$\textcircled{1} \cdot H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})}$$

$$\text{Table 5.2} \quad X(e^{j\omega}) = \frac{1}{1 - \frac{1}{2}e^{-j\omega}}$$

$$Y[n] = (n+1)\left(\frac{1}{2}\right)^n u[n] - 3\left(\frac{1}{2}\right)^n u[n]$$

$$\text{Table 5.2} \quad Y(e^{j\omega}) = \frac{1}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2} - 3 \frac{1}{1 - \frac{1}{2}e^{-j\omega}}$$

$$= \frac{1 - 3 + \frac{3}{2}e^{-j\omega}}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2}$$

$$= \frac{-2 + \frac{3}{2}e^{-j\omega}}{\left(1 - \frac{1}{2}e^{-j\omega}\right)^2}$$

0.5 mark

$$\Rightarrow H(e^{j\omega}) = \frac{-2 + \frac{3}{2}e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}} //$$

$$\circ h[n]: H(e^{j\omega}) = -2 \frac{1}{1 - \frac{1}{2}e^{-j\omega}} + \frac{3}{2} \frac{e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}}$$

$$\text{Table 5.1} \\ \text{5.2} \Rightarrow h[n] = -2 \left(\frac{1}{2}\right)^n u[n] + \frac{3}{2} \left(\frac{1}{2}\right)^{n-1} u[n-1] //$$

0.5 mark

$$= -2 \left(\frac{1}{2}\right)^n u[n] + 3 \left(\frac{1}{2}\right)^n u[n-1]$$

$$= -2 \delta[n] + \left(\frac{1}{2}\right)^n u[n-1]$$

② $h[n] = 0 \quad \forall n < 0 \Rightarrow \text{causal} //$

0.5 $\sum_{n=-\infty}^{\infty} |h[n]| = 2 + \sum_{n=1}^{\infty} \left(\frac{1}{2}\right)^n = 1 + \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n$

$$= 1 + \frac{1}{1 - \frac{1}{2}} = 3$$

0.5 $\Rightarrow \text{stable} //$

③ $H^{inv}(e^{j\omega}) = \frac{1}{H(e^{j\omega})} = \frac{1 - \frac{1}{2} e^{-j\omega}}{-2 + \frac{3}{2} e^{-j\omega}}$

$$= \frac{-\frac{1}{2} + \frac{1}{4} e^{-j\omega}}{1 - \frac{3}{4} e^{-j\omega}}$$

$$= -\frac{1}{2} \frac{1}{1 - \frac{3}{4} e^{-j\omega}} + \frac{1}{4} \frac{e^{-j\omega}}{1 - \frac{3}{4} e^{-j\omega}}$$

Table 5.1
5.2 0.5 mark

$$\Rightarrow h^{inv}[n] = -\frac{1}{2} \left(\frac{3}{4}\right)^n u[n] + \frac{1}{4} \left(\frac{3}{4}\right)^{n-1} u[n-1]$$

$$= -\frac{1}{2} \left(\frac{3}{4}\right)^n u[n] + \frac{1}{3} \left(\frac{3}{4}\right)^n u[n-1]$$

$$= -\frac{1}{2} \delta[n] - \frac{1}{6} \left(\frac{3}{4}\right)^n u[n-1]$$

$h[n] = 0$ for $n < 0 \Rightarrow \text{causal}$ 0.25

$\sum_n |h[n]| < \infty \Rightarrow \text{stable}$

0.25 marks

④ • $H(e^{j\omega}) = \frac{-2 + \frac{3}{2} e^{-j\omega}}{1 - \frac{1}{2} e^{-j\omega}} = \frac{Y(e^{j\omega})}{X(e^{j\omega})}$

$$\left(-2 + \frac{3}{2} e^{-j\omega}\right) X(e^{j\omega}) = \left(1 - \frac{1}{2} e^{-j\omega}\right) Y(e^{j\omega})$$

0.5 mark $-2x[n] + \frac{3}{2}x[n-1] = y[n] - \frac{1}{2}y[n-1]$

• inverse system: change roles of x and y

0.5 marks $-2y[n] + \frac{3}{2}y[n-1] = x[n] - \frac{1}{2}x[n-1]$